



August 25, 2023

Solving Max-Cut and QUBO Problems via Low-Rank Methods

Joint work with Valentin Durante, Federal University of Toulouse

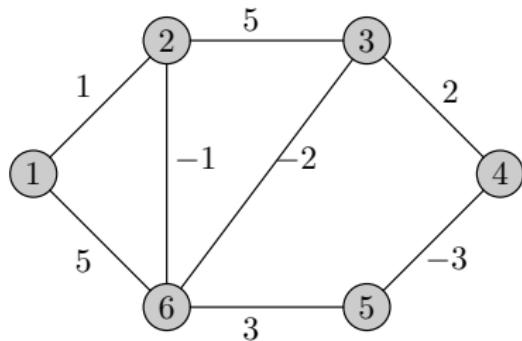
J. Schwidder

EUROpt 2023



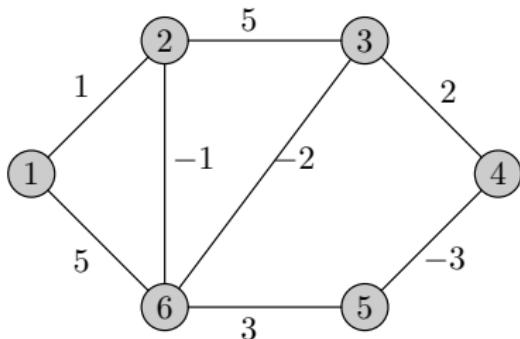
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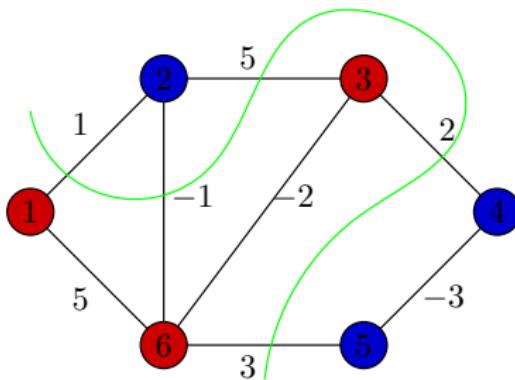
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$$\delta(S) := \{ij \in E : i \in S, j \notin S\}$$

is called the *cut* induced by S .

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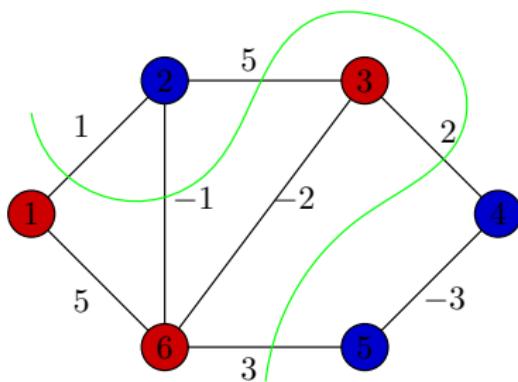
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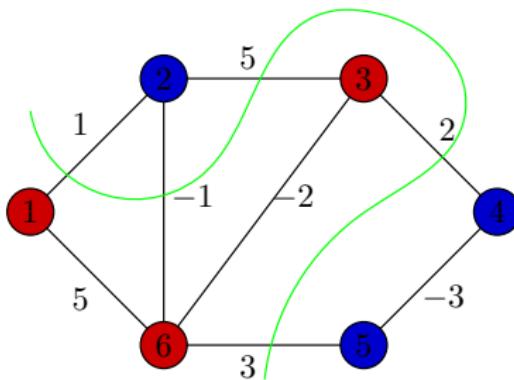
Max-Cut Problem

Find a maximum cut in G , i.e., an optimal solution of

$$\max_{S \subseteq V} \sum_{ij \in \delta(S)} a_{ij}. \quad (\text{MC})$$

The (Weighted) Max-Cut Problem

Given: undirected graph $G = (V, E)$ with edge weights $a \in \mathbb{R}^E$



Max-Cut Problem

- ▶ \mathcal{NP} -hard
- ▶ polynomial time solvable in special cases (e.g., planar graphs)
- ▶ 0.878-approximation algorithm for $a \geq 0$ (Goemans & Williamson, 1995)
(Mahajan & Ramesh, 1995)
- ▶ LP-based approaches efficient for sparse graphs

Quadratic Unconstrained Binary Optimization (QUBO)

- ▶ Laplacian matrix $L := \text{Diag}(Ae) - A$
 - ▶ weighted adjacency matrix $A = (a_{ij})_{ij}$
 - ▶ all-ones vector e

Formulation of Max-Cut

$$(MC) \Leftrightarrow \begin{array}{ll} \max & \frac{1}{4}x^\top L x \\ \text{s. t.} & x \in \{-1, 1\}^n \end{array}$$

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Quadratic unconstrained binary optimization

Given $C \in \mathbb{R}^{n \times n}$, solve

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Goal: branch-and-cut solver for (MC) and (QUBO)

(QUBO) is quite general...

- ▶ minimization \leftrightarrow maximization
- ▶ linear quadratic objective $x^\top Qx + q^\top x$
- ▶ variables in $\{0, 1\}^n \leftrightarrow \{-1, 1\}^n$
- ▶ linear constraints $Ax = b$

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Linearly constrained binary quadratic problems

$$\begin{aligned} & \min \quad x^\top Qx + q^\top x \\ \text{s. t. } & Ax = b \\ & x \in \{0, 1\}^n \end{aligned} \tag{BQP}$$

where $Q \in \mathbb{R}^{n \times n}$, $q \in \mathbb{R}^n$, $A \in \mathbb{R}^{m \times n}$, $b \in \mathbb{R}^m$.

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- ▶ Any BQP instance in n variables can be reformulated as a QUBO instance in $n + 1$ variables! (Lasserre, 2016)

Semidefinite Programming Relaxation

We introduce $X := xx^\top$:

- $x^\top Cx = \langle C, xx^\top \rangle = \langle C, X \rangle$
- $\text{diag}(X) = e$
- $X \succeq 0$
- $\text{rank}(X) = 1$

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Equivalent formulations (Laurent & Poljak, 1995)

$$\begin{aligned} \max \quad & x^\top Cx \\ \text{s. t. } & x \in \{-1, 1\}^n \end{aligned} \qquad \Leftrightarrow \qquad$$

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Semidefinite programming relaxation

$$\begin{array}{ll} \max & x^\top Cx \\ \text{s. t.} & x \in \{-1, 1\}^n \end{array} \leq \begin{array}{l} \max \quad \langle C, X \rangle \\ \text{s. t.} \quad \text{diag}(X) = e \\ \quad \quad X \succeq 0 \\ \quad \quad \text{rank}(X) = 1 \end{array}$$

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Optimal value of SDP relaxation is at most...

- ▶ 57% larger if $C \succeq 0$. (Nesterov, 1998)
- ▶ 13.83% larger for (MC) if $a \geq 0$. (Goemans & Williamson, 1995)

Branch-and-Cut Approaches

- ▶ SDP-based solvers in the literature:
 - ▶ BiqMac (2010)
 - ▶ MADAM (2021)
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- ▶ $\mathcal{O}(n^3)$ triangle inequalities:

$$X_{ij} + X_{ik} + X_{jk} \geq -1, \quad i < j < k$$

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- ▶ MADAM & BiqBin: $\mathcal{O}(n^5)$ pentagonal, $\mathcal{O}(n^7)$ heptagonal cuts
- ▶ exact separation only for triangle inequalities

Lagrangian Relaxation

SDP with a subset of m triangle inequalities $\langle A_i, X \rangle \leq b_i$:

$$\begin{aligned} f^* := \max \quad & \langle C, X \rangle \\ \text{s. t. } & X \in \mathcal{E} \quad (\Leftrightarrow \text{diag}(X) = e, \quad X \succeq 0) \\ & \mathcal{A}(X) \leq b \end{aligned}$$

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Dualizing $\mathcal{A}(X) \leq b$ yields:

partial Lagrangian: $\mathcal{L}(X, \gamma) := \langle C, X \rangle - \gamma^\top (\mathcal{A}(X) - b)$

dual function: $f(\gamma) := \max_{X \in \mathcal{E}} \mathcal{L}(X, \gamma) = b^\top \gamma + \max_{X \in \mathcal{E}} \langle C - \mathcal{A}^\top(\gamma), X \rangle$

► adjoint operator: $\mathcal{A}^\top(\gamma) := \sum_{i=1}^m \gamma_i A_i$

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- ▶ dual problem:

$$f^* = \min_{\gamma \geq 0} f(\gamma)$$

Evaluating f

$$f(\gamma) = b^\top \gamma + \max_{X \in \mathcal{E}} \langle C - \mathcal{A}^\top(\gamma), X \rangle$$

- ▶ for $\tilde{C} = C - \mathcal{A}^\top(\gamma)$, we have to solve

$$\begin{aligned} & \max && \langle \tilde{C}, X \rangle \\ & \text{s. t.} && X \in \mathcal{E} \end{aligned} \tag{*}$$

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Burer-Monteiro factorization for SDPs (Burer & Monteiro, 2003)

Factorize $X = V^\top V \succeq 0$, $V = (v_1 | \dots | v_n) \in \mathbb{R}^{k \times n}$, $k \leq n$, and solve

$$\begin{aligned} & \max && \langle \tilde{C}, V^\top V \rangle \\ & \text{s. t.} && V^\top V \in \mathcal{E}. \end{aligned} \tag{SDP-vec}$$

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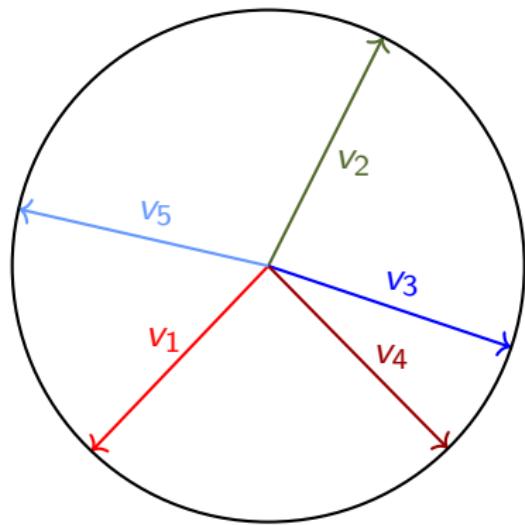
$$\begin{aligned} & \max && \langle \tilde{C}, V^\top V \rangle \\ & \text{s. t.} && V^\top V \in \mathcal{E}. \end{aligned} \tag{SDP-vec}$$

- $V^\top V \in \mathcal{E} \Leftrightarrow \|v_i\| = 1$, $i = 1, \dots, n$
- $(*) \Leftrightarrow (\text{SDP-vec})$ for $k = \lceil \sqrt{2n} \rceil$ (Barvinok, 1995; Pataki, 1998)

Geometric Interpretation

Optimization problem (SDP-vec)

$$\begin{aligned} \max \quad & \langle \tilde{C}, V^\top V \rangle = \sum_{i,j=1}^n \tilde{C}_{ij} v_i^\top v_j \\ \text{s. t.} \quad & \|v_i\| = 1, \quad i = 1, \dots, n \end{aligned} \tag{SDP-vec}$$



$$\begin{aligned} v_i^\top v_j &= \|v_i\| \cdot \|v_j\| \cdot \cos \angle(v_i, v_j) \\ &= \cos \angle(v_i, v_j) \end{aligned}$$

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Coordinate ascent

We fix all columns except v_i .

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We fix all columns except v_i . (SDP-vec) reduces to

$$\begin{aligned} \max \quad & g^\top v_i \\ \text{s. t.} \quad & \|v_i\| = 1, \quad v_i \in \mathbb{R}^k \end{aligned}$$

where $g = \sum_{j=1, j \neq i}^n \tilde{C}_{ij} v_j = V \cdot \tilde{C}_{(i)} - \tilde{C}_{ii} v_i$.

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where $g = \sum_{j=1, j \neq i}^n \tilde{C}_{ij} v_j = V \cdot \tilde{C}_{(i)} - \tilde{C}_{ii} v_i$.

- ▶ closed-form solution: $v_i = \frac{g}{\|g\|}$ if $g \neq 0$

Low-Rank Methods

Algorithm 1: Mixing Method (Wang et al., 2018)

Input: $\tilde{C} \in \mathbb{R}^{n \times n}$ with $\text{diag}(\tilde{C}) = 0$, $k \in \mathbb{N}_{\geq 1}$

Output: approximate solution $V = (v_1 | \dots | v_n) \in \mathbb{R}^{k \times n}$ of (SDP-vec)

for $i \leftarrow 1$ **to** n **do**

$v_i \leftarrow$ random vector on the unit sphere \mathcal{S}^{k-1} ;

while not yet converged **do**

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$v_i \leftarrow \frac{V \cdot \tilde{C}_{(i)}}{\|V \cdot \tilde{C}_{(i)}\|};$

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- ▶ block-coordinate maximization (Erdogdu et al., 2022)
- ▶ momentum-based acceleration (Kim et al., 2021)
- ▶ bilinear decomposition, ADMM (Chen & Goulart, 2023)

When do we stop the mixing method?

Notation

- ▶ V_k : matrix V after iteration k
- ▶ $f_k = \langle \tilde{C}, V_k^\top V_k \rangle$, function value after iteration k
- ▶ $\Delta_k = f_k - f_{k-1}$, objective improvement in iteration k

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Stopping criterion: relative step tolerance

- ▶ stop if $\frac{\|V_{k-1} - V_k\|_F}{1 + \|V_{k-1}\|_F} < \varepsilon \approx 0.01$

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Stopping criterion: estimated gap (see MIXSAT solver, Wang & Kolter, 2019)

- ▶ stop if $0 < \varepsilon = \frac{\Delta_{k-1} \Delta_k}{\Delta_{k-1} - \Delta_k}$ small

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- ▶ **caveat:** the actual optimum can be smaller or larger!

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- ▶ stop **if** $\frac{\|V_{k-1} - V_k\|_F}{1 + \|V_{k-1}\|_F} < \varepsilon \approx 0.01$

Stopping criterion: estimated gap (see MIXSAT solver, Wang & Kolter, 2019)

- ▶ stop **if** $0 < \varepsilon = \frac{\Delta_{k-1} \Delta_k}{\Delta_{k-1} - \Delta_k}$ small $\Rightarrow f^* \approx f_k + \varepsilon$
- ▶ **caveat:** the actual optimum can be smaller or **larger!**

How do we bound f^* from above (**dualbound**)?

Upper Bounds via Weak Duality

Primal-dual pair

$$\begin{array}{ll} \max & \langle \tilde{C}, X \rangle \\ \text{s. t.} & \text{diag}(X) = e \\ & X \succeq 0 \end{array}$$

(SDP)

$$\begin{array}{ll} \min & e^\top y \\ \text{s. t.} & \text{Diag}(y) - \tilde{C} \succeq 0 \\ & y \in \mathbb{R}^n \end{array}$$

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Let $V^* = \lim_{k \rightarrow \infty} V_k$. Then $y_i = \|V^* \cdot \tilde{C}_{(i)}\|_2$ is optimal for (DSDP).

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- ▶ feasible dual variables: $y = \tilde{y} - \lambda_{\min}(\text{Diag}(\tilde{y}) - \tilde{C})e$

Approximately Solving the Dual Problem

$$\min_{\gamma \geq 0} f(\gamma) = \min_{\gamma \geq 0} \left\{ b^\top \gamma + \max_{X \in \mathcal{E}} \langle C - A^\top(\gamma), X \rangle \right\}$$

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- ▶ dynamic bundle approach for SDPs by Fischer et al. (2003)
- ▶ implementation similar to BiqMac and BiqBin

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Speed:

- ▶ fast approximate function and subgradient evaluation
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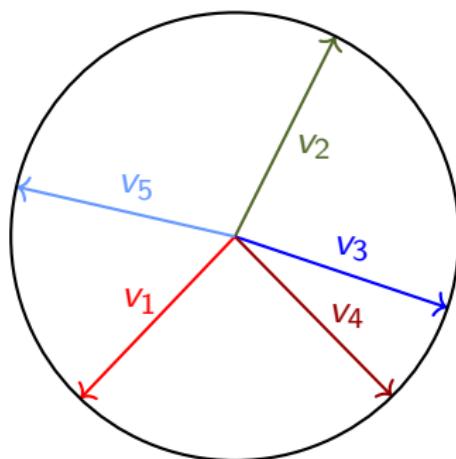
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Primal heuristic:

- ▶ Goemans-Williamson hyperplane rounding
 - ▶ one-opt and two-opt local search
 - ▶ ‘biased’ hyperplanes

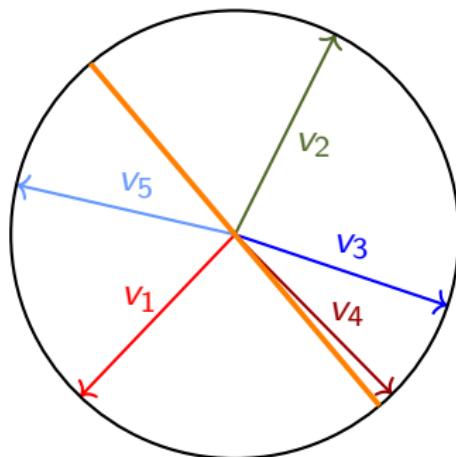
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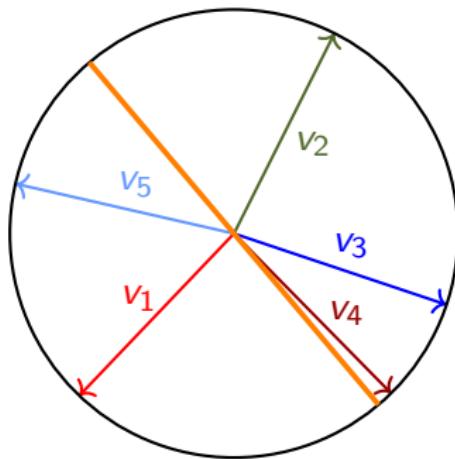
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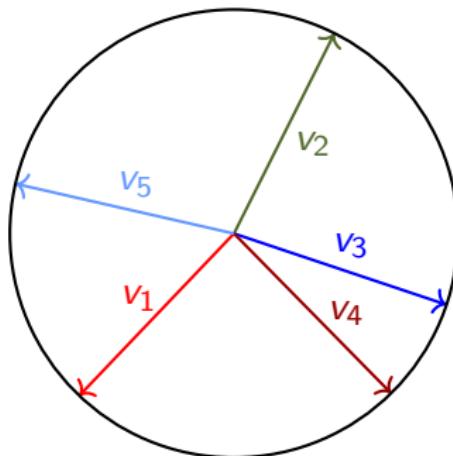
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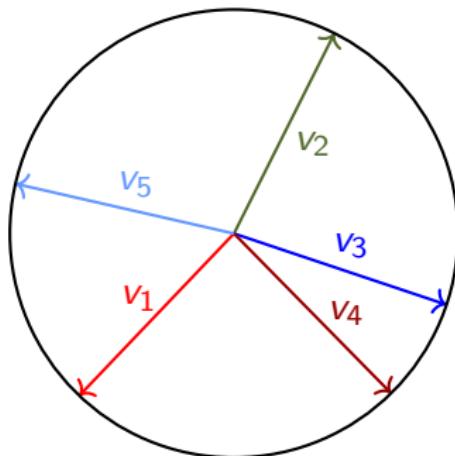
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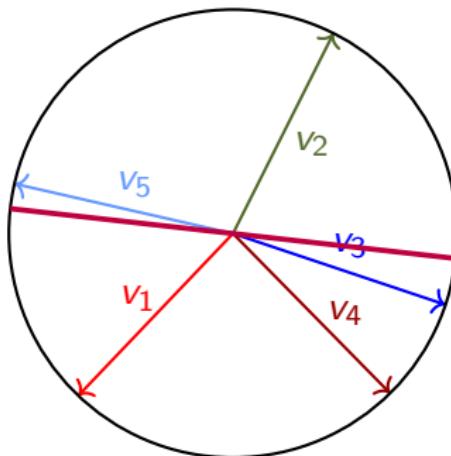
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Computational Results I

- ▶ Erdős–Rényi graphs $G_{100,\frac{1}{2}}$ (unweighted)

instance	BiqMac		MADAM		our solver	
	time	nodes	time	nodes	time	nodes
g05_100.0	555.16	531	98.33	195	17.19	751
g05_100.1	3547.17	3643	494.10	705	84.78	3888
g05_100.2	115.87	127	40.07	43	5.31	305
g05_100.3	1308.85	1215	129.60	497	29.48	1292
g05_100.4	71.03	69	9.71	11	2.68	99
g05_100.5	116.16	129	28.63	31	5.31	203
g05_100.6	177.22	193	29.52	47	6.52	253
g05_100.7	332.35	337	75.31	73	11.74	495
g05_100.8	291.28	275	35.78	67	8.50	367
g05_100.9	321.10	277	47.34	101	9.57	403

Table: CPU times (s) and B&B nodes for ‘g05’ instances.

Computational Results II

- ▶ Erdős–Rényi graphs $G_{180, \frac{1}{2}}$ (unweighted)
- ▶ MADAM: parallel run on 20 CPUs (240 cores in total)
- ▶ our solver: single-threaded
- ▶ (*): $240 \cdot \frac{\text{time}_{\text{MADAM}}}{\text{time}_{\text{our solver}}}$

instance	MADAM		our solver		
	time	nodes	time	nodes	(*)
g05_180.0	671.23	148,617	12164.62	190,859	13.24
g05_180.1	670.63	137,665	12981.40	204,257	12.40
g05_180.2	1116.24	281,215	20693.20	325,851	12.95
g05_180.3	3706.61	786,457	90040.88	1,084,351	9.88
g05_180.4	5209.59	1,556,485	72889.44	987,595	17.15
g05_180.5	8964.00	2,333,997	171576.67	2,803,449	12.54
g05_180.6	10542.41	2,298,681	215391.59	2,926,271	11.75

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Thank you!