



February 17, 2021

# Facility Layout Problems: Solution Approaches and Practical Difficulties

Jan Schwiddessen

Institut für Mathematik

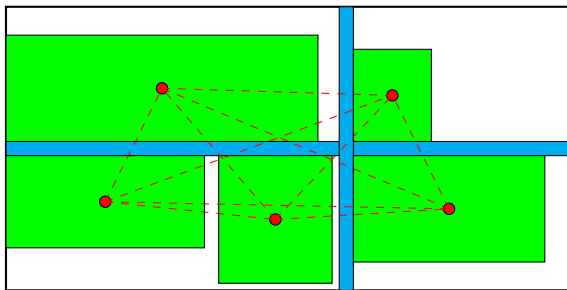
# Outline

- 1 The single row facility layout problem (SRFLP)
- 2 LP, SDP and Lagrangian relaxation
- 3 LP-based approaches
- 4 Semidefinite relaxations
- 5 An efficient algorithmic approach



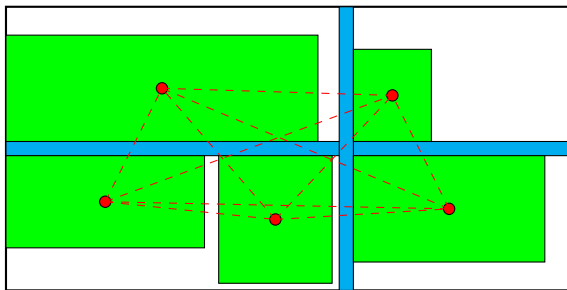
# Facility Layout Planning

- find an optimal placement of machines inside a factory according to a given objective function



# Facility Layout Planning

- find an optimal placement of machines inside a factory according to a given objective function



- applications:
  - VLSI circuit design
  - manufacturing systems
  - ...
- very hard problem in general

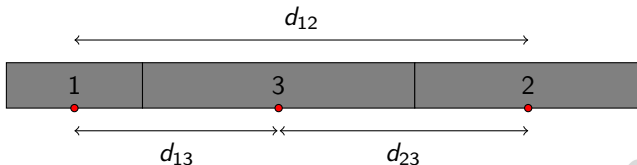


# Single Row Facility Layout Problem (SRFLP)

- Given:**
- ▶  $n$  one-dimensional machines  $[n] := \{1, \dots, n\}$
  - ▶ lengths  $\ell_i \geq 0$ ,  $i \in [n]$
  - ▶ pairwise transport weights  $c_{ij} \geq 0$ ,  $i, j \in [n]$ ,  $i < j$

**Goal:** find a permutation  $\pi \in \Pi_n$  of the machines minimizing the total weighted sum of center-to-center distances  $d_{ij}^\pi$  between all pairs of machines:

$$\min_{\pi \in \Pi_n} \sum_{\substack{i, j \in [n] \\ i < j}} c_{ij} d_{ij}^\pi$$



# Literature review

- ▶ first considered by Simmons (1969)
- ▶ many applications were identified
- ▶ many heuristic approaches in recent years
- ▶ exact solution methods include: B&B, MILP, DP, ILP, SDP

## Best exact solution methods:

- ▶ Amaral (2009): Integer Linear Programming ( $n \leq 35$ )
- ▶ Hungerländer & Rendl (2013): semidefinite relaxations ( $n \leq 42$ )

## Related problems:

- ▶ equidistant SRFLP is a special case of the QAP
- ▶ SRFLP generalizes the (weighted) Linear Arrangement Problem
- ▶ other facility layout or ordering problems



# How can we solve a combinatorial optimization problem?

- ▶ by enumeration of all possible solutions
- ▶ by a suitable combinatorial algorithm
- ▶ by computing dual bounds (using mathematical programming)

Solving an instance of the SRFLP to optimality requires two things:

- ▶ a feasible solution with some objective value  $k$  (upper bound)
- ▶ a prove that the optimal value is at least  $k$  (lower bound)

↔ linear and semidefinite relaxations



# (Mixed-Integer) Linear Programming

Let  $c, x \in \mathbb{R}^n$ ,  $A \in \mathbb{R}^{m \times n}$ ,  $b \in \mathbb{R}^m$ .

$$\begin{array}{ll} \min & c^\top x \\ \text{s.t.} & Ax = b \\ & x \geq 0 \\ & x_i \in \mathbb{Z}, \quad i \in \mathcal{I} \end{array} \quad (\text{MILP})$$

*Linear relaxation:*

$$\begin{array}{ll} \min & c^\top x \\ \text{s.t.} & Ax = b \\ & x \geq 0 \end{array} \quad (\text{LP})$$

- ▶  $\text{opt}(\text{LP}) \leq \text{opt}(\text{MILP})$
- ▶ (LP) can be solved in polynomial time
- ▶ we can also add inequality constraints or free variables





# (Mixed-Integer) Linear Programming

Let  $c, x \in \mathbb{R}^n$ ,  $A \in \mathbb{R}^{m \times n}$ ,  $b \in \mathbb{R}^m$ .

$$\begin{array}{ll} \min & c^\top x \\ \text{s.t.} & Ax = b \\ & x \geq 0 \\ & x_i \in \mathbb{Z}, \quad i \in \mathcal{I} \end{array} \quad (\text{MILP})$$

*Linear relaxation:*

$$\begin{array}{ll} \min & c^\top x \\ \text{s.t.} & Ax = b \\ & x \geq 0 \end{array} \quad (\text{LP})$$

- ▶  $\text{opt}(\text{LP}) \leq \text{opt}(\text{MILP})$
- ▶ (LP) can be solved in polynomial time
- ▶ we can also add inequality constraints or free variables



# Semidefinite Programming (SDP)

- ▶  $\mathcal{S}_n := \{A \in \mathbb{R}^{n \times n} : A = A^\top\}$
- ▶  $\langle A, B \rangle := \sum_{i=1}^n \sum_{j=1}^n a_{ij} b_{ij}$  for any  $A, B \in \mathcal{S}_n$

Let  $C, A_1, \dots, A_m \in \mathcal{S}_n$  and  $b \in \mathbb{R}^m$ . A semidefinite program in standard form can be written as

$$\begin{array}{ll} \min & \langle C, X \rangle \\ \text{s.t.} & \langle A_i, X \rangle = b_i, \quad i = 1, \dots, m \\ & X \succeq 0. \end{array} \quad (\text{SDP})$$

- ▶ we also write  $\mathcal{A}(X) = b$ , where  $\mathcal{A}: \mathcal{S}_n \rightarrow \mathbb{R}^m$  is a linear operator of the form

$$\mathcal{A}(X) = \begin{pmatrix} \langle A_1, X \rangle \\ \vdots \\ \langle A_m, X \rangle \end{pmatrix}$$

- ▶ adjoint operator:  $\mathcal{A}^\top(y) := \mathcal{A}^*(y) = \sum_{i=1}^m y_i A_i$  for all  $y \in \mathbb{R}^m$
- ▶ well-posed SDPs can be solved in polynomial time



# Semidefinite Programming (SDP)

- ▶  $\mathcal{S}_n := \{A \in \mathbb{R}^{n \times n} : A = A^\top\}$
- ▶  $\langle A, B \rangle := \sum_{i=1}^n \sum_{j=1}^n a_{ij} b_{ij}$  for any  $A, B \in \mathcal{S}_n$

Let  $C, A_1, \dots, A_m \in \mathcal{S}_n$  and  $b \in \mathbb{R}^m$ . A semidefinite program in standard form can be written as

$$\begin{aligned} \min \quad & \langle C, X \rangle \\ \text{s.t.} \quad & \langle A_i, X \rangle = b_i, \quad i = 1, \dots, m \\ & X \succeq 0. \end{aligned} \tag{SDP}$$

- ▶ we also write  $\mathcal{A}(X) = b$ , where  $\mathcal{A}: \mathcal{S}_n \rightarrow \mathbb{R}^m$  is a linear operator of the form

$$\mathcal{A}(X) = \begin{pmatrix} \langle A_1, X \rangle \\ \vdots \\ \langle A_m, X \rangle \end{pmatrix}$$

- ▶ adjoint operator:  $\mathcal{A}^\top(y) := \mathcal{A}^*(y) = \sum_{i=1}^m y_i A_i$  for all  $y \in \mathbb{R}^m$
- ▶ well-posed SDPs can be solved in polynomial time



# Semidefinite Programming (SDP)

- ▶  $\mathcal{S}_n := \{A \in \mathbb{R}^{n \times n} : A = A^\top\}$
- ▶  $\langle A, B \rangle := \sum_{i=1}^n \sum_{j=1}^n a_{ij} b_{ij}$  for any  $A, B \in \mathcal{S}_n$

Let  $C, A_1, \dots, A_m \in \mathcal{S}_n$  and  $b \in \mathbb{R}^m$ . A semidefinite program in standard form can be written as

$$\begin{aligned} \min \quad & \langle C, X \rangle \\ \text{s.t.} \quad & \langle A_i, X \rangle = b_i, \quad i = 1, \dots, m \\ & X \succeq 0. \end{aligned} \tag{SDP}$$

- ▶ we also write  $\mathcal{A}(X) = b$ , where  $\mathcal{A}: \mathcal{S}_n \rightarrow \mathbb{R}^m$  is a linear operator of the form

$$\mathcal{A}(X) = \begin{pmatrix} \langle A_1, X \rangle \\ \vdots \\ \langle A_m, X \rangle \end{pmatrix}$$

- ▶ adjoint operator:  $\mathcal{A}^\top(y) := \mathcal{A}^*(y) = \sum_{i=1}^m y_i A_i$  for all  $y \in \mathbb{R}^m$
- ▶ well-posed SDPs can be solved in polynomial time



# Lagrangian relaxation

$$\begin{aligned} \min \quad & \langle C, X \rangle \\ (*) \quad \text{s.t.} \quad & \mathcal{A}(X) = b \quad (\Leftrightarrow \mathcal{A}(X) - b = 0) \\ & X \in \mathcal{X} \subseteq \mathcal{S}_n \end{aligned}$$

- ▶ assumption: (\*) without  $\mathcal{A}(X) = b \in \mathbb{R}^m$  much easier to solve
- ▶ primal variable  $X$  and dual variable  $\mu \in \mathbb{R}^m$
- ▶ Lagrangian:  $\mathcal{L}(X; \mu) := \langle C, X \rangle + \mu^\top (\mathcal{A}(X) - b)$
- ▶ dual function:  $f(\mu) := \inf_{X \in \mathcal{X}} \mathcal{L}(X; \mu)$
- ▶ weak duality:  $f(\mu) \leq \langle C, X \rangle$  for all  $X$  feasible in (\*) and all  $\mu \in \mathbb{R}^m$ , since  $\mu^\top (\mathcal{A}(X) - b) = 0$  for all  $X$  feasible in (\*)
- ▶ dual problem:

$$\begin{aligned} \sup \quad & f(\mu) \\ \text{s.t.} \quad & \mu \in \mathbb{R}^m \end{aligned}$$



# Lagrangian relaxation

$$\begin{aligned} \min \quad & \langle C, X \rangle \\ (*) \quad \text{s.t.} \quad & \mathcal{A}(X) = b \quad (\Leftrightarrow \mathcal{A}(X) - b = 0) \\ & X \in \mathcal{X} \subseteq \mathcal{S}_n \end{aligned}$$

- ▶ assumption: (\*) without  $\mathcal{A}(X) = b \in \mathbb{R}^m$  much easier to solve
- ▶ primal variable  $X$  and dual variable  $\mu \in \mathbb{R}^m$
- ▶ *Lagrangian*:  $\mathcal{L}(X; \mu) := \langle C, X \rangle + \mu^\top (\mathcal{A}(X) - b)$
- ▶ *dual function*:  $f(\mu) := \inf_{X \in \mathcal{X}} \mathcal{L}(X; \mu)$
- ▶ *weak duality*:  $f(\mu) \leq \langle C, X \rangle$  for all  $X$  feasible in (\*) and all  $\mu \in \mathbb{R}^m$ , since  $\mu^\top (\mathcal{A}(X) - b) = 0$  for all  $X$  feasible in (\*)
- ▶ dual problem:

$$\begin{aligned} \sup \quad & f(\mu) \\ \text{s.t.} \quad & \mu \in \mathbb{R}^m \end{aligned}$$



# Lagrangian relaxation

$$\begin{aligned} & \min \quad \langle C, X \rangle \\ (*) \quad & \text{s.t.} \quad \mathcal{A}(X) = b \quad (\Leftrightarrow \mathcal{A}(X) - b = 0) \\ & \quad \quad X \in \mathcal{X} \subseteq \mathcal{S}_n \end{aligned}$$

- ▶ assumption: (\*) without  $\mathcal{A}(X) = b \in \mathbb{R}^m$  much easier to solve
- ▶ primal variable  $X$  and dual variable  $\mu \in \mathbb{R}^m$
- ▶ *Lagrangian*:  $\mathcal{L}(X; \mu) := \langle C, X \rangle + \mu^\top (\mathcal{A}(X) - b)$
- ▶ *dual function*:  $f(\mu) := \inf_{X \in \mathcal{X}} \mathcal{L}(X; \mu)$
- ▶ *weak duality*:  $f(\mu) \leq \langle C, X \rangle$  for all  $X$  feasible in (\*) and all  $\mu \in \mathbb{R}^m$ , since  $\mu^\top (\mathcal{A}(X) - b) = 0$  for all  $X$  feasible in (\*)
- ▶ dual problem:

$$\begin{aligned} & \sup \quad f(\mu) \\ & \text{s.t.} \quad \mu \in \mathbb{R}^m \end{aligned}$$



# MILP formulation by Love & Wong (1976) I

Intuitive modelling approach with the following variables:

- ▶ ordering variables  $u_{ij} \in \{0, 1\}$ ,  $i, j \in [n]$ ,  $i \neq j$ , with the meaning

$$u_{ij} = \begin{cases} 1, & \text{if machine } i \text{ lies to the left of machine } j \\ 0, & \text{otherwise.} \end{cases}$$

- ▶ position variables  $p_i$  ( $\hat{=}$  abscissa of the centers),  $i \in [n]$ , with

$$\frac{\ell_i}{2} \leq p_i \leq M - \frac{\ell_i}{2},$$

where  $M := \sum_{i \in [n]} \ell_i$

- ▶ distance variables  $d_{ij} \geq 0$ ,  $i, j \in [n]$ ,  $i < j$





# MILP formulation by Love & Wong (1976) II

$$\begin{array}{ll}\min & \sum_{\substack{i,j \in [n] \\ i < j}} c_{ij} d_{ij} \\ \text{s.t.} & u_{ij} + u_{ji} = 1, \quad i, j \in [n], \quad i < j, \\ & d_{ij} \geq p_i - p_j, \quad i, j \in [n], \quad i < j, \\ & d_{ij} \geq p_j - p_i, \quad i, j \in [n], \quad i < j, \\ & p_i + \frac{\ell_i + \ell_j}{2} \leq p_j + M(1 - u_{ij}), \quad i, j \in [n], \quad i \neq j, \\ & \frac{\ell_i}{2} \leq p_i \leq M - \frac{\ell_i}{2}, \quad i \in [n], \\ & d_{ij} \geq 0, \quad i, j \in [n], \quad i < j, \\ & u_{i,j} \in \{0, 1\}, \quad i, j \in [n], \quad i \neq j.\end{array}$$

Very poor linear relaxation: optimal solution is given by

$$\begin{aligned}d_{ij} &:= 0, \quad i, j \in [n], \quad i < j, \\ p_i &:= \max \{ \ell_j : j \in [n] \}, \quad i \in [n], \\ u_{ij} &:= \frac{1}{2}, \quad i, j \in [n], \quad i \neq j.\end{aligned}$$



# MILP formulation by Love & Wong (1976) II

$$\begin{aligned} \min \quad & \sum_{\substack{i,j \in [n] \\ i < j}} c_{ij} d_{ij} \\ \text{s.t.} \quad & u_{ij} + u_{ji} = 1, & i, j \in [n], \ i < j, \\ & d_{ij} \geq p_i - p_j, & i, j \in [n], \ i < j, \\ & d_{ij} \geq p_j - p_i, & i, j \in [n], \ i < j, \\ & p_i + \frac{\ell_i + \ell_j}{2} \leq p_j + M(1 - u_{ij}), & i, j \in [n], \ i \neq j, \\ & \frac{\ell_i}{2} \leq p_i \leq M - \frac{\ell_i}{2}, & i \in [n], \\ & d_{ij} \geq 0, & i, j \in [n], \ i < j, \\ & u_{i,j} \in \{0, 1\}, & i, j \in [n], \ i \neq j. \end{aligned}$$

Very poor linear relaxation: optimal solution is given by

$$\begin{aligned} d_{ij} &:= 0, \quad i, j \in [n], \ i < j, \\ p_i &:= \max \{ \ell_j : j \in [n] \}, \quad i \in [n], \\ u_{ij} &:= \frac{1}{2}, \quad i, j \in [n], \ i \neq j. \end{aligned}$$



# Why distance variables should be avoided

- ▶ several incremental improvements, e.g., Amaral (2006, 2008)
- ▶ significant by Amaral & Letchford (2013): they solved an instance with  $n = 30$  in about one day using the lower bounds within a branch-and-bound approach

## However:

- ▶ still relatively weak lower bounds
- ▶ theoretical evidence that the approach is rather limited
- ▶ feasible set depends on the concrete instance
- ▶ only a 'local' modelling, weak coupling



# Betweenness variables (Amaral, 2009)

$b_{ijk} \in \{0, 1\}$ ,  $i, j, k \in [n]$ ,  $|\{i, j, k\}| = 3$ ,  $i < k$ , with the meaning

$$b_{ijk} = \begin{cases} 1, & j \text{ lies between } i \text{ and } k \\ 0, & \text{otherwise.} \end{cases}$$

Motivation:

$$d_{ij} = \frac{\ell_i + \ell_j}{2} + \sum_{k \in [n] \setminus \{i, j\}} \ell_k b_{ikj}, \quad i, j \in [n], \quad i < j$$

SRFLP formulation:

$$\begin{aligned} \min \quad & \sum_{\substack{i, j \in [n] \\ i < j}} c_{ij} \sum_{k \in [n] \setminus \{i, j\}} \ell_k b_{ikj} + \sum_{\substack{i, j \in [n] \\ i < j}} c_{ij} \frac{\ell_i + \ell_j}{2} \\ \text{s.t.} \quad & \text{the betweenness variables represent a permutation} \end{aligned}$$



# Betweenness model (Amaral, 2009)

$$\begin{aligned}
 \min \quad & \sum_{\substack{i,j \in [n] \\ i < j}} c_{ij} \sum_{k \in [n] \setminus \{i,j\}} \ell_k b_{ikj} + \sum_{\substack{i,j \in [n] \\ i < j}} c_{ij} \frac{\ell_i + \ell_j}{2} \\
 \text{s.t.} \quad & b_{ijk} + b_{ikj} + b_{jik} = 1, \quad i, j, k \in [n], i < j < k \\
 & b_{ihj} + b_{ihk} + b_{jkh} \leq 2, \quad i, j, k, h \in [n], |\{i, j, k, h\}| = 4, i < j < k \\
 & -b_{ihj} + b_{ihk} + b_{jkh} \geq 0, \quad i, j, k, h \in [n], |\{i, j, k, h\}| = 4, i < j < k \\
 & b_{ihj} - b_{ihk} + b_{jkh} \geq 0, \quad i, j, k, h \in [n], |\{i, j, k, h\}| = 4, i < j < k \\
 & b_{ihj} + b_{ihk} - b_{jkh} \geq 0, \quad i, j, k, h \in [n], |\{i, j, k, h\}| = 4, i < j < k \\
 & b_{ijk} \in \{0, 1\}, \quad i, j, k \in [n], |\{i, j, k\}| = 3, i < k
 \end{aligned}$$

Up to symmetry, there are three cases:

$$\begin{array}{cccccc}
 \dots & i & \dots & j & \dots & k & \dots \\
 \dots & i & \dots & k & \dots & j & \dots \\
 \dots & j & \dots & i & \dots & k & \dots
 \end{array}$$

$h$  can only lie between zero **or** two pairs of  $(i, j)$ ,  $(i, k)$ ,  $(j, k)$ !



# Properties of the betweenness formulation

## Strengths:

- ▶ 'global' modelling, strong coupling
- ▶ linear relaxation often yields the optimal value
- ▶ additional inequalities known

## Weaknesses:

- ▶ simplex method extremely slow
- ▶ linear relaxation can already be insufficient for  $n = 6$

How can we find even better lower bounds?

↪ semidefinite programming (SDP)!



# Bivalent quadratic formulation I

Again we use **ordering variables**, but now with values in  $\{-1, 1\}$ :

$$x_{ij} = \begin{cases} +1, & \text{if } i \text{ lies to the left of } j \\ -1, & \text{otherwise} \end{cases}, \quad i, j \in [n], i \neq j.$$

Connection to betweenness variables:

$$b_{ijk} = \frac{1 - y_{ji}y_{jk}}{2}, \quad j < i < k, \quad b_{ijk} = \frac{1 + y_{ij}y_{jk}}{2}, \quad j < i < k,$$
$$b_{ijk} = \frac{1 - y_{ij}y_{kj}}{2}, \quad j < i < k.$$

The following *three-cycle-equations* must be satisfied:

$$x_{ij}x_{jk} - x_{ij}x_{ik} - x_{ik}x_{jk} = -1, \quad i, j, k \in [n], i < j < k.$$



# Bivalent quadratic formulation II

$$\begin{aligned} \min \quad & K - \sum_{\substack{i,j \in [n] \\ i < j}} \frac{c_{ij}}{2} \left( \sum_{\substack{k \in [n] \\ k < i}} \ell_k x_{ki} x_{kj} - \sum_{\substack{k \in [n] \\ i < k < j}} \ell_k x_{ik} x_{kj} + \sum_{\substack{k \in [n] \\ k > j}} \ell_k x_{ik} x_{jk} \right) \\ \text{s.t.} \quad & x_{ij} x_{jk} - x_{ij} x_{ik} - x_{ik} x_{jk} = -1, & i, j, k \in [n], i < j < k, \\ & x_{ij} \in \{-1, 1\}, & i, j \in [n], i < j. \end{aligned}$$

Consider the matrix  $X = xx^\top$  with entries  $X_{ij,kl} = x_{ij}x_{kl}$ . We have:

- ▶  $X_{ij,ij} = 1$ ; we write  $\text{diag}(X) = e = (1, \dots, 1)^\top$
- ▶  $\text{rk}(X) = 1$
- ▶  $X \succeq 0$ , since  $X = X^\top$  and  $v^\top X v = v^\top x x^\top v = (v^\top x)^2 \geq 0$





# Bivalent quadratic formulation II

$$\begin{aligned} \min \quad & K - \sum_{\substack{i,j \in [n] \\ i < j}} \frac{c_{ij}}{2} \left( \sum_{\substack{k \in [n] \\ k < i}} \ell_k x_{ki} x_{kj} - \sum_{\substack{k \in [n] \\ i < k < j}} \ell_k x_{ik} x_{kj} + \sum_{\substack{k \in [n] \\ k > j}} \ell_k x_{ik} x_{jk} \right) \\ \text{s.t.} \quad & x_{ij} x_{jk} - x_{ij} x_{ik} - x_{ik} x_{jk} = -1, & i, j, k \in [n], i < j < k, \\ & x_{ij} \in \{-1, 1\}, & i, j \in [n], i < j. \end{aligned}$$

Consider the matrix  $X = xx^\top$  with entries  $X_{ij,kl} = x_{ij}x_{kl}$ . We have:

- ▶  $X_{ij,ij} = 1$ ; we write  $\text{diag}(X) = e = (1, \dots, 1)^\top$
- ▶  $\text{rk}(X) = 1$
- ▶  $X \succeq 0$ , since  $X = X^\top$  and  $v^\top X v = v^\top x x^\top v = (v^\top x)^2 \geq 0$



# Semidefinite relaxation

## Matrix-based formulation:

$$\begin{array}{ll}\min & \langle C, X \rangle + K \\ \text{s.t.} & X_{ij,jk} - X_{ij,ik} - X_{ik,jk} = -1, \quad i, j, k \in [n], \ i < j < k, \\ & \text{diag}(X) = e \\ & \text{rk}(X) = 1 \\ & X \succeq 0\end{array}$$

## Semidefinite relaxation:

$$\begin{array}{ll}\min & \langle C, X \rangle + K \\ \text{s.t.} & X_{ij,jk} - X_{ij,ik} - X_{ik,jk} = -1, \quad i, j, k \in [n], \ i < j < k, \\ & \text{diag}(X) = e \\ & X \succeq 0\end{array}$$



# Semidefinite relaxation

## Matrix-based formulation:

$$\begin{array}{ll}\min & \langle C, X \rangle + K \\ \text{s.t.} & X_{ij,jk} - X_{ij,ik} - X_{ik,jk} = -1, \quad i, j, k \in [n], \ i < j < k, \\ & \text{diag}(X) = e \\ & \text{rk}(X) = 1 \\ & X \succeq 0\end{array}$$

## Semidefinite relaxation:

$$\begin{array}{ll}\min & \langle C, X \rangle + K \\ \text{s.t.} & X_{ij,jk} - X_{ij,ik} - X_{ik,jk} = -1, \quad i, j, k \in [n], \ i < j < k, \\ & \text{diag}(X) = e \\ & X \succeq 0\end{array}$$



# Strengthened semidefinite relaxation

Anjos et al. (2006), Hungerländer & Rendl (2013) also added the so-called *triangle inequalities*:

$$\begin{aligned} \min \quad & \langle C, X \rangle + K \\ \text{s.t.} \quad & X_{ij,jk} - X_{ij,ik} - X_{ik,jk} = -1, \quad i, j, k \in [n], i < j < k \\ & \text{diag}(X) = e \\ & X_{ij} + X_{ik} + X_{jk} \geq -1, \quad 1 \leq i < j < k \leq n(n-1)/2 \\ & X_{ij} - X_{ik} - X_{jk} \geq -1, \quad 1 \leq i < j < k \leq n(n-1)/2 \\ & -X_{ij} + X_{ik} - X_{jk} \geq -1, \quad 1 \leq i < j < k \leq n(n-1)/2 \\ & -X_{ij} - X_{ik} + X_{jk} \geq -1, \quad 1 \leq i < j < k \leq n(n-1)/2 \\ & X \succeq 0 \end{aligned} \quad (\text{SDP}_{\text{tri}})$$

## Proposition

*The semidefinite relaxation ( $\text{SDP}_{\text{tri}}$ ) is at least as strong than the linear relaxation of the betweenness model.*

- ▶ more inequalities: pentagonal inequalities, hexagonal inequalities, heptagonal inequalities, ...



# Strengthened semidefinite relaxation

Anjos et al. (2006), Hungerländer & Rendl (2013) also added the so-called *triangle inequalities*:

$$\begin{aligned} \min \quad & \langle C, X \rangle + K \\ \text{s.t.} \quad & X_{ij,jk} - X_{ij,ik} - X_{ik,jk} = -1, \quad i, j, k \in [n], i < j < k \\ & \text{diag}(X) = e \\ & X_{ij} + X_{ik} + X_{jk} \geq -1, \quad 1 \leq i < j < k \leq n(n-1)/2 \\ & X_{ij} - X_{ik} - X_{jk} \geq -1, \quad 1 \leq i < j < k \leq n(n-1)/2 \\ & -X_{ij} + X_{ik} - X_{jk} \geq -1, \quad 1 \leq i < j < k \leq n(n-1)/2 \\ & -X_{ij} - X_{ik} + X_{jk} \geq -1, \quad 1 \leq i < j < k \leq n(n-1)/2 \\ & X \succeq 0 \end{aligned} \quad (\text{SDP}_{\text{tri}})$$

## Proposition

*The semidefinite relaxation ( $\text{SDP}_{\text{tri}}$ ) is at least as strong than the linear relaxation of the betweenness model.*

- ▶ more inequalities: pentagonal inequalities, hexagonal inequalities, heptagonal inequalities, ...



# How can we solve the semidefinite relaxation?

- ▶ we cannot include all inequalities at the same time
- ▶ standard interior-point methods require a running time of  $\mathcal{O}(n^9)$ !

↪ we must use a customized, approximative first-order method that is much faster in practice!

We consider the following optimization problem:

$$\begin{array}{ll}\min & \langle C, X \rangle \\ \text{s.t.} & \mathcal{A}(X) \leq a \\ & \mathcal{B}(X) = e \\ & X \succeq 0 \\ & \text{rk}(X) = 1 \Leftrightarrow \|X\|_F^2 = n^2\end{array}$$

## Proposition (spherical constraint)

Let  $X \in \{Y \in \mathbb{R}^{n \times n} : \text{diag}(Y) = e, Y \succeq 0\}$ . Then we have

$$\|X\|_F \leq n, \quad \text{and} \quad \text{rk}(X) = 1 \quad \Longleftrightarrow \quad \|X\|_F = n.$$

# How can we solve the semidefinite relaxation?

- ▶ we cannot include all inequalities at the same time
- ▶ standard interior-point methods require a running time of  $\mathcal{O}(n^9)$ !

↪ we must use a customized, approximative first-order method that is much faster in practice!

We consider the following optimization problem:

$$\begin{array}{ll}\min & \langle C, X \rangle \\ \text{s.t.} & \mathcal{A}(X) \leq a \\ & \mathcal{B}(X) = e \\ & X \succeq 0 \\ & \text{rk}(X) = 1 \Leftrightarrow \|X\|_F^2 = n^2\end{array}$$

## Proposition (spherical constraint)

Let  $X \in \{Y \in \mathbb{R}^{n \times n} : \text{diag}(Y) = e, Y \succeq 0\}$ . Then we have

$$\|X\|_F \leq n, \quad \text{and} \quad \text{rk}(X) = 1 \quad \Longleftrightarrow \quad \|X\|_F = n.$$

# How can we solve the semidefinite relaxation?

- ▶ we cannot include all inequalities at the same time
- ▶ standard interior-point methods require a running time of  $\mathcal{O}(n^9)$ !

↪ we must use a customized, approximative first-order method that is much faster in practice!

We consider the following optimization problem:

$$\begin{aligned} \min \quad & \langle C, X \rangle \\ \text{s.t.} \quad & \mathcal{A}(X) \leq a \\ & \mathcal{B}(X) = e \\ & X \succeq 0 \\ & \text{rk}(X) = 1 \Leftrightarrow \|X\|_F^2 = n^2 \end{aligned}$$

## Proposition (spherical constraint)

Let  $X \in \{Y \in \mathbb{R}^{n \times n} : \text{diag}(Y) = e, Y \succeq 0\}$ . Then we have

$$\|X\|_F \leq n, \quad \text{and} \quad \text{rk}(X) = 1 \quad \Longleftrightarrow \quad \|X\|_F = n.$$



# How can we solve the semidefinite relaxation?

- ▶ we cannot include all inequalities at the same time
- ▶ standard interior-point methods require a running time of  $\mathcal{O}(n^9)$ !

↪ we must use a customized, approximative first-order method that is much faster in practice!

We consider the following optimization problem:

$$\begin{array}{ll}\min & \langle C, X \rangle \\ \text{s.t.} & \mathcal{A}(X) \leq a \\ & \mathcal{B}(X) = e \\ & X \succeq 0 \\ & \text{rk}(X) = 1 \Leftrightarrow \|X\|_F^2 = n^2\end{array}$$

## Proposition (spherical constraint)

Let  $X \in \{Y \in \mathbb{R}^{n \times n} : \text{diag}(Y) = e, Y \succeq 0\}$ . Then we have

$$\|X\|_F \leq n, \quad \text{and} \quad \text{rk}(X) = 1 \quad \Longleftrightarrow \quad \|X\|_F = n.$$

# Applying Lagrangian relaxation

primal variable:  $X \in \mathcal{S}_n$

dual variables:  $\lambda \geq 0, \mu, Z \succeq 0, \alpha$

Lagrangian:

$$\mathcal{L}(X; \lambda, \mu, Z, \alpha) := \langle C, X \rangle + \lambda^\top (\mathcal{A}(X) - a) + \mu^\top (\mathcal{B}(X) - e) + \frac{\alpha}{2} (\|X\|^2 - n^2) - \langle Z, X \rangle$$

Dual function:

$$\begin{aligned} f(\lambda, \mu, Z, \alpha) &:= \inf_{X \in \mathcal{S}_n} \mathcal{L}(X; \lambda, \mu, Z, \alpha) \\ &= c(\lambda, \mu, \alpha) + \inf_{X \in \mathcal{S}_n} \left\{ \frac{\alpha}{2} \|X\|^2 + \langle C(\lambda, \mu) - Z, X \rangle \right\}, \end{aligned}$$

where

$$\begin{aligned} c(\lambda, \mu, \alpha) &:= -a^\top \lambda - e^\top \mu - \frac{\alpha}{2} n^2 \\ C(\lambda, \mu) &:= C + \mathcal{A}^\top(\lambda) + \mathcal{B}^\top(\mu) \end{aligned}$$

Dual problem:

$$\sup_{\lambda \geq 0, \mu, Z \succeq 0, \alpha} f(\lambda, \mu, Z, \alpha)$$



# Algorithmic approach I

## Theorem (Malick & Roupin (2012))

Given dual variables  $\lambda \geq 0$ ,  $\mu$ ,  $Z \succeq 0$  and  $\alpha > 0$ , the minimum of the Lagrangian  $\mathcal{L}(X; \lambda, \mu, Z, \alpha)$  is attained at

$$X = \frac{1}{\alpha} \left( Z - C - \mathcal{A}^\top(\lambda) - \mathcal{B}^\top(\mu) \right)$$

and the dual function can be written

$$f(\lambda, \mu, Z, \alpha) = -a^\top \lambda - e^\top \mu - \frac{\alpha}{2} n^2 - \frac{1}{2\alpha} \left\| C + \mathcal{A}^\top(\lambda) + \mathcal{B}^\top(\mu) - Z \right\|^2.$$

## Theorem (Malick & Roupin (2012))

Given dual variables  $(\lambda, \mu, \alpha)$  with  $\alpha > 0$ , the dual function can be maximized over  $Z$ ; the resulting simplified dual function is

$$\begin{aligned} f(\lambda, \mu, \alpha) &:= \max_{Z \succeq 0} f(\lambda, \mu, Z, \alpha) \\ &= -a^\top \lambda - e^\top \mu - \frac{\alpha}{2} n^2 - \frac{1}{2\alpha} \left\| \left[ C + \mathcal{A}^\top(\lambda) + \mathcal{B}^\top(\mu) \right]_- \right\|^2, \end{aligned}$$

where  $[\cdot]_-$  denotes the projection onto the cone of negative semidefinite matrices.

# Algorithmic approach II

- ▶  $f(\lambda, \mu, \alpha)$  is differentiable at any  $(\lambda, \mu, \alpha)$  with  $\alpha > 0$  and the partial derivatives are

$$\partial_{\lambda} f(\lambda, \mu, \alpha) = -\frac{1}{\alpha} \mathcal{A} \left( [C + \mathcal{A}^{\top}(\lambda) + \mathcal{B}^{\top}(\mu)]_- \right) - a$$

$$\partial_{\mu} f(\lambda, \mu, \alpha) = -\frac{1}{\alpha} \mathcal{B} \left( [C + \mathcal{A}^{\top}(\lambda) + \mathcal{B}^{\top}(\mu)]_- \right) - e$$

## Algorithmic idea:

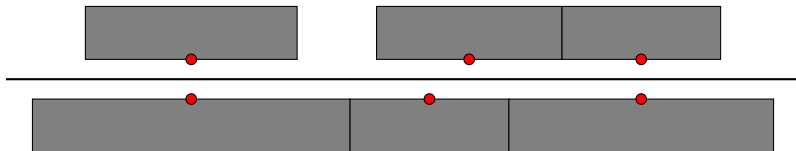
- ▶ fix  $\bar{\alpha} > 0$  and optimize  $f(\lambda, \mu, \bar{\alpha})$  over  $\lambda \geq 0$  and  $\mu$
- ▶ in the SRFLP setting: by taking  $\alpha > 0$  small enough, we can get arbitrarily close to the bound of the semidefinite relaxation

## Results:

- ▶ outperforms all approaches in the literature (faster, stronger bounds)
- ▶ by using additional pentagonal, hexagonal and heptagonal inequalities, SRFLP instances with up to  $n = 81$  could be solved for the first time



# The Double Row Facility Layout Problem (DRFLP)



- ▶ solution is no permutation
- ▶ gaps are possible
- ▶ distances may be zero
- ▶ can distance variables be avoided?
- ▶ is there any good semidefinite relaxation?
- ▶ if yes, how can it be solved?

